Xplorer: A System for Visual Analysis of Sensor-based Motor Activity Predictions



Marco Cavallo, Çağatay Demiralp

Fig. 1. Xplorer interface. The main view shows a timeline containing a set of stacked linear tracks, which can either represent classification events (a) or ground-truth labels (b). A dedicated protocol track (c) can be used to annotate time windows, while a synchronized video player (d) enables users to validate the context of event predictions. Customization of the appearance of the tracks can be performed from the left collapsible sidebar (d). A command line interface (f) is also available to users.

Abstract-

Due to the large diffusion of wearable devices, the task of detecting motor activities from sensor data is becoming increasingly common in a wide range of applications. During the development of predictive models for activity recognition, data scientists generally rely on performance metrics (such as accuracy score) for evaluating and comparing the performance of classification algorithms. While these numerical estimates represent a straightforward way to summarize the effectiveness of a model, they convey little insights on the causes of misclassified events, not offering enough clues for data scientists to improve their algorithms.

In this paper we present BlueSky Xplorer, an interactive visualization system to analyze, debug and compare the output of multiple predictive models at different levels of granularity. We combine classification results on multi-sensor data with the context of usage of each sensor and with ground truth information (such as textual labels and videos), representing them as temporally-aligned linear tracks. We then define an algebraic language over these tracks that enables users to quickly identify classification errors and to visually reason on the performance of classifiers.

We demonstrate the usefulness of our tool by applying it to a real-world example, involving the development of models for assessing the symptoms of Parkinsons disease. In particular, we show how Xplorer was used to improve the performance of classification models and to discover problems in data temporal alignment.

Index Terms—Visualization, sequence, sensor data, classification, model validation, track algebra, query, Parkinson.

1 INTRODUCTION

• Marco Cavallo, IBM Research. E-mail: mcavall@us.ibm.com

• Çagatay Demiralp, IBM Research. E-mail: cagatay.demiralp@us.ibm.com Manuscript received xx xxx. 201x; accepted

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The large diffusion of consumer-level wearable devices has opened many possibilities related to activity monitoring. Smart watches and devices such as Fitbit [1] are increasingly used by people to track their daily motor activity, whereas a wide variety of biosensors is starting to play an important role in patient monitoring. The task of detecting motor activities such as walking from sensor data is thus becoming very popular in the fields of data science and machine learning. The development of these prediction models generally relies on validating their performance on a database of labeled sensor data. Numerical metrics such as accuracy score are often computed to establish how well a classifier can identify specific activity events. Based on these metrics, data scientists can compare the performance of different prediction models and establish which of them can be deployed. In less trivial applications, data scientists may also have to evaluate the combined performance of multiple classifiers, which can be based on the input of different sets of sensors.

While performance metrics try to condense the effectiveness of a model to ready-to-use numerical estimates, they are sometimes not sufficient for a deeper understanding of *why* a prediction model seems to perform better than another one. In particular, the lack of contextual information does not allow data scientists to analyze classification results at a more granular scale, making it difficult to gain insights on the possible reasons behind each misclassification. On top of not being adequately helpful for suggesting how to improve predictive models, the computation of metrics also assumes the presence of correct ground-truth labels, assumption that may not always hold — especially for manually-generated motion activity labels.

We introduce a novel visualization system, Xplorer, to interactively analyze the classification results of sensor-based predictive models. In particular, Xplorer enables users to debug and compare multiple classifiers up to the level of granularity of a single prediction, providing different ways to validate the performance of each model. Our contribution consists in (1) a new method for visually coordinating classification results with ground-truth information (i.e. labels, video) and in (2) an algebraic language for quickly identifying relevant prediction events. In particular, Xplorer aims at facilitating the interpretation of classification results, enabling data scientists to reason on the causes of misclassifications and to improve their predictive models. We note that our system does not aim at gaining insights on the internal behavior of a predictive model, rather it serves the purpose of analyzing its output.

To illustrate the usefulness of our system, we report a real-life use case, involving the development of predictive models for identifying relevant motor activities in Parkinson's disease. We study the usage of Xplorer by a mixed group of fourteen people, composed of both data scientists and business people working on the same project. We demonstrate how Xplorer proved to be fundamental for visually validating and comparing predictive models, for reasoning on the causes of mispredictions, and for understanding the trade-offs in the usage of different sensors. We further observe how the system, being independent from the implementation details of each predictive model, facilitated the discussion among data scientists and between science and business people in general.

2 RELATED WORK

We build on earlier work on temporal and sequential data visualization (e.g., [3–5,8]) along with interactive systems that query and compose visualizations through algebraic operations (e.g., [3,6,7]). The visual design of Xplorer takes inspiration from genome browsers. USCS Human Genome Browser [5] visualizes requested portions of the human genome as aligned, linear tracks, which can be added, removed and reordered based on need. Fundamental interactions include zooming and panning to enable fine-grained exploration of the data, often represented as horizontal bars of variable length. These features are also commonly found in multimedia editors, where tracks typically represent audio or video sources. In the context of data analysis, Time-ART [8] and ChronoViz [4] provide synchronized, interactive visual representations of multiple data streams, enabling navigation and annotation of time-coded data.

In order to formulate or validate complex hypotheses about the data, earlier work formulates algebraic operations over visual elements. For example, *invis* [3] provides a simple algebraic approach to inspecting RNA sequences, where mutations can be visually aggregated using the logical operators AND, OR, and NOT. Polaris [6], introduces a table algebra, extending Wilkinson's grammar of graphics [7]. Xplorer builds on earlier work and introduces a basic track algebra, facilitating the ability to effectively filter, compose, and compare track representations of classification results.

3 XPLORER

The interface of Xplorer (Fig. 1) is composed of a main view, where classification results and labels are represented as linear tracks stacked



Fig. 2. Track definition. A track in Xplorer corresponds to a list of non-overlapping time-periods ("events"). There are two types of tracks: classifier tracks and label tracks. The former contains probability scores associated to each event and can be visualized either as an area chart or as a horizontal bars ("blocks"), whereas the latter contains only information about time intervals. Classifier tracks can be converted into label tracks by applying a threshold on their prediction scores.

vertically. A track visually corresponds to a set of non-overlapping colored blocks, positioned over a common timeline.

In the case of classifier tracks (Fig. 1a), a block corresponds to a single prediction or to a set of consecutive identical predictions, which may result in blocks of variable length. If the output of a classifier is binary, the block is made visible only when the activity is detected. If a predictive model outputs a probability score, the block is instead generated by applying a classifier-specific threshold to the continuous prediction (Fig. 2). Here the color opacity of the block is determined by its associated probability score (e.g. the higher the probability of a detected activity, the more intense the color).

In the case of label tracks (Fig. 1b), each block corresponds to a textual label (e.g. "Walking", "Person is sitting"), characterized by a start and end time which determine its position and length. Labels can be either algorithmically generated or manually defined by a human, and are often used as ground-truth or as a reference for validating classifier tracks. The color of blocks in a label track, differently than in classifier tracks, has always the same opacity. A particular type of label track, called *protocol track* (Fig. 1c), can hold different unique labels on the same timeline, given they do not overlap with each other. The protocol track is generally used as a time reference track, where each block corresponds to a specific task and is identified by a different categorical color.

Whereas all other temporal data is represented as a linear track, video information is shown in a separate container (Fig. 1d), which can be dragged across the interface and freely resized by the user.

The interface of Xplorer further includes some auxiliary modal windows and a left sidebar, from which users can decide which tracks to visualize and easily zoom to specific events contained in the protocol track.

3.1 Interactions

Track information can be analyzed at different levels of granularity through zooming and panning, which are performed with the mouse wheel and drag actions. In order to maintain the time alignment among predictions and labels, each movement transform is applied equally to all tracks. By double clicking on a block or by selecting the name of a protocol label from the left sidebar, all tracks are conveniently scaled to show a close-up of the moment of interest. By hovering on a block, information about the correspondent prediction or label is shown (e.g. author, duration) as a tooltip. In particular, the tooltip includes classifier-specific attribute values (e.g. "tremor frequency", "angular velocity") in the case of classifier tracks (Fig. 5).

Each classifier track further includes four buttons, enabling the user to 1) increase its height for better visibility, 2) play consecutively the videos of all detected activities, 3) display information about the underlying predictive model (e.g. sensors, prediction window and threshold used), and 4) switch between two different visualization modes. Fig. 2 explains how a classifier track can be represented also as an area chart, visualizing a continuous probability score over time. This mode is particularly useful for observing how the threshold of a classifier determines which events are positively predicted (and thus generate a block). The threshold can be dynamically changed by the user by moving the red horizontal line shown in Fig. 2, thus avoiding the recomputation of



Fig. 3. Classifiers validation with track algebra. In the above figure, A represents a classifier track and B represents a label track containing ground-truth labels. By computing the intersection and the subtraction of the two tracks, it is possible to obtain new tracks corresponding to correct and incorrect predictions.

classification results. All tracks can additionally be sorted by mouse dragging, allowing the user to better compare them visually.

3.2 Track Visual Algebra

While analyzing each track separately may be sufficient for some applications, in many cases the possibility to combine different tracks could be essential. For instance, a user may want to analyze the output of a tremor classifier only when a different classifier is predicting no walking movement. Similarly, a user may want to consider all moments in which a subject is stationary, thus needing to unify the labels associated to "Sitting" with the labels associated to "Standing". To enable reasoning beyond the scope of single classifiers and labels, we define a visual algebra that allows to generate new tracks as a combination of existing tracks. Operations such as addition, subtraction, logic conjunction and disjunction can be applied to both classifier and label tracks with a different semantic meaning.

Fig. 3 illustrates how the most common operators can be used as a form of classifier validation. If we denote *A* a classifier track and *B* a label track used as ground-truth, $A \land B$ corresponds to the intersection of both tracks, that is to the events that were correctly predicted by the model (true positives). Similarly, we can define difference between track *A* and track *B* as a new track were all block instances of *B* are removed from *A*. This way, the track A - B will contain all classifier detections that do not match any ground truth label (false positives), while B - A will conversely represent labeled events that were not identified by the predictive model (false negatives).

The power of the track algebra consists in enabling users to quickly combine tracks to validate complex hypotheses about the classification process. In particular, in presence of ground-truth labels, it makes the identification of misclassified events visually straightforward. In combination with the video functionality, it also enables to play consecutively all false positive and all false negative predictions for a particular classifier. This way, the user can visually validate the performance of his predictive model and reason on the causes of each single misprediction.

3.3 Command Line

Xplorer interface features a command line interface for enabling users to quickly perform complex interactions, such as track manipulation through visual algebra. Fig. 3.4 shows a list of the most common commands that can be executed from the command line. Each command is composed of one operator and one or two operands, which can be track identifiers or numerical values. A track identifier is automatically generated as a combination of the track name, author and version (e.g. the first version of the "Sleeping" classifier created by author "John" will generate the id "SleepingJohn1.0") and is made available through auto-completion. For instance, while typing "threshold sle" the command line will automatically infer which available track is best suited for the operator "threshold", highlight it in the main view and offer the suggested completion "threshold SleepingJohn1.0". When a command generates a new track, this one is added to the main view and its name and identifier are automatically defined based on the operation performed.



Validation is currently performed from 10:22:30 to 10:25:01

Fig. 4. Performance metrics. Xplorer features a modal window to display different measures of classification performance. The user chooses which classification track and which label track to consider, then metrics such as AUC (Area Under the Curve), Jaccard index, precision, recall, and F1 score are shown. An interactive ROC (Receiver Operating Characteristic) curve is also displayed to help the user choose an adequate threshold for the selected classifier.

3.4 Classifiers Validation

While observing a classifier track *A* and a ground-truth label track *B* next to each other, it is intuitive to understand that the performance of the predictive model depends on how much the blocks of each track are aligned with each other. Optimally, for each block in *A* there should exist a block in *B* of equal length, whose start end and points match the ones of *A*. Misclassifications and other prediction-related errors may however make one of this two blocks absent or misaligned. A straightforward, numerical way to quantify the visual overlap of two tracks is the Jaccard distance, computed as their intersection over union. By sampling each track into a sequence of prediction values or binary labels, it is possible to compute different performance metrics commonly used in data science, such as accuracy score, precision, recall and F1 score.

Note that the value of all these metrics often depends on the threshold applied to the continuous prediction of a classifier. The choice of the threshold is often critical since it allows to balance the amount of true positives and false negatives allowed for a predictive model. For this reason, we include in the Xplorer interface a modal window displaying also a Receiver Operating Characteristic (ROC) plot (Fig. 4) with its related Area Under the Curve (AUC) score, a threshold-independent performance metric. In particular, the user can observe the percentage of true positives and false negatives associated to the current threshold and see how this percentage changes by modifying it.

4 USE CASE: BLUESKY PROJECT

BlueSky project [2] aims at deploying predictive models to automatically assess the symptoms of Parkinson's disease using wearable sensors. Xplorer was used by a team of fourteen data scientists and business people as a companion tool over most of the project.

A total of six wearable IMU sensors were used, worn by Parkinson's disease subjects over sessions (visits) of about one hour. The sensors measured accelerometer, gyroscope and magnetometer information at 128Hz and were placed on the wrists, feet, chest and back of the patients. During each visit, all subjects performed the same set of predefined tasks, according to a single clinical protocol. A group of external technicians took care of recording sessions, labeling specific activities and time-stamping the execution of tasks. Sensor data, ground-truth labels and video files were all stored in a single database, that all data scientists could access during the development of their predictive models.

Each time a data scientist produced a new version of a model or algorithm, its classification results were loaded into our visualization

Operation	P_1	P_2	Description
negate	T_1		Generates $\neg T$
add / union	T_1	T_2	Generates $T_1 \lor T_2$
intersection	T_1	T_2	Generates $T_1 \wedge T_2$
errors	T_1	T_2	Generates $T_1 \oplus T_2$
subtract	T_1	T_2	Generates $T_1 - T_2$
play	T		Plays all events in track T
threshold	<i>C</i>	Float	Changes C's threshold to a fixed value
show / hide	T		Shows / hides track T
jaccard	T_1	T_2	Jaccard distance between T_1 and T_2
roc	<i>C</i>	L	Computes ROC curve and AUC score
report	<i>C</i>	L	Computes precision, recall and F1 score
transform	<i>C</i>		Thresholds C and generates an L track
rename	T		Renames a track

Table 1. Commands available from the Xplorer command line. P_1 and P_2 are the parameters required by each command. T is a placeholder for a generic track's identifier, whereas C and L indicate a classifier and a label track respectively. Track type conversion is automatically handled according to the definition explained in Fig. 2.



Fig. 5. Sample tracks from the BlueSky Project. By observing the pattern of green boxes (label tracks), it is straightforward to observe that the subject is alternating walking to turning movements. While the alignment of the classifier tracks "Walking" and "Turning" with their correspondent ground-truth labels seems satisfactory, we may note that the predictive model "Body Turn" appears to detect events too early. By inspecting sensors usage in the video and the attributes associated to each prediction (shown as a tooltip), data scientists can try to debug their prediction models. The possibility to dynamically change the threshold of a classifier (as shown on the "Turning" track) further aims at a better understanding of predicted motor events.

system and analyzed by the whole team during group meetings. Xplorer demonstrated in fact to be a great tool for team discussion, enabling even non-technical people to understand classification results. Without knowing the implementation details of each predictive model, it was sufficient to visually check the alignment of tracks and further validate it with the video.

The playback functionality, in combination with the track algebra, proved to be a fundamental feature for quickly identifying mispredictions. For instance, by subtracting the "Walk" label track to the "Walk" classifier track and by playing the resulting track, it was possible to observe all cases in which the classifier wrongly predicted the subject was walking (false positives). By observing the video and the task labels, data scientists realized that, since the model was using the sensor worn on the chest, it was incorrectly detecting movements such as arising from the chair and coat buttoning. Similarly, the "Step detector" classifier track (based on sensors worn on the shoes) showed false positives in correspondence of feet tremor, particularly common when subjects were sitting with their legs crossed. Based on these insights, data scientists decided to re-train their classification models with data from different sensors or by including in the training set the activities that had been misclassified.

Another widely used feature was the possibility to inspect information about each single prediction. After having noticed that the two hand classifiers "Pronation-supination" and "Tremor" were biased by the action of walking, data scientists were able to mouse over mispredicted events and observe the attributes computed by their predictive models. In this case, each prediction held numerical information about hand rotation angle, hand rotation speed, tremor frequency and tremor amplitude. By analyzing these attributes, data scientists were able to filter out the movements happening at specific frequencies associated to walking, thus making their model more robust.

Xplorer was also useful in handling ground-truth labels. The track algebra allowed to quickly combine partial labels (e.g. the tracks "Short-Walk" and "LongWalk" were combined into a single track "Walking") and to identify mismatches with other reference tracks and the video. In particular, Xplorer opened a discussion on the quality and reliability of labels, which otherwise would have never been questioned. By observing labels associated to false negatives, data scientists observed an incoherent labeling and an unclear definition of movements such as walking and turning. Should few short steps considered a walk? Should a larger rotation of the chest be considered a turn? If so, would they be useful to consider for the purpose of the project? Similarly, false positives showed the absence of a large amount of labels, which were not annotated by human operators because the subject was out of camera. Data scientists further noticed correct classification results were often misaligned with ground-truth labels: with the help of the video feature, it was demonstrated that humangenerated labels generally occurred before a subject started a movement. For instance, a technician would annotate a walk whenever a subject showed the intention to move, without waiting for him to make a first step.

Finally, our visualization system played a relevant role in the phase of model validation. Balancing the amount of true positives and false negatives was of fundamental importance for the project, which required being certain of positive predictions more than correctly predicting all events. The possibility to dynamically change the threshold applied to classifier tracks, combined with the ROC curve visualization, helped data scientists visually and quantitatively observe prediction changes.

5 CONCLUSION

In this paper we present a new visualization tool, Xplorer, to query and visually analyze classification results originated from sensor temporal data. In particular, Xplorer offers contextual information such as ground truth labels and video that data scientists can use to better interpret the performance of predictive models. Through a real-life use case, we demonstrate how our system is suitable for understanding the causes of misclassifications, improving classifiers performance and identifying early on possible systemic errors in the data.

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